

On the Behavior of Marginal and Conditional Akaike Information Criteria in Linear Mixed Models

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Akaike Information Criterion

- Most commonly used model choice criterion for **comparing parametric models**.

- Definition:

$$\text{AIC} = -2l(\hat{\boldsymbol{\psi}}) + 2k.$$

where $l(\hat{\boldsymbol{\psi}})$ is the log-likelihood evaluated at the maximum likelihood estimate $\hat{\boldsymbol{\psi}}$ for the unknown parameter vector $\boldsymbol{\psi}$ and $k = \dim(\boldsymbol{\psi})$ is the number of parameters.

- Properties:

- Compromise between **model fit** and **model complexity**.
- Allows to compare non-nested models.
- Selects rather too many than too few variables in variable selection problems.

- Data \mathbf{y} generated from a **true underlying model** described in terms of density $g(\cdot)$.
- Approximate the true model by a parametric class of models $f_\psi(\cdot) = f(\cdot; \psi)$.
- Measure the discrepancy between a model $f_\psi(\cdot)$ and the truth $g(\cdot)$ by the **Kullback-Leibler distance**

$$\begin{aligned} K(f_\psi, g) &= \int [\log(g(\mathbf{z})) - \log(f_\psi(\mathbf{z}))] g(\mathbf{z}) d\mathbf{z} \\ &= \mathbf{E}_z [\log(g(\mathbf{z})) - \log(f_\psi(\mathbf{z}))]. \end{aligned}$$

where \mathbf{z} is an independent replicate following the same distribution as \mathbf{y} .

- Decision rule: Out of a sequence of models, **choose the one that minimises $K(f_\psi, g)$** .

- In practice, the parameter ψ will have to be **estimated as $\hat{\psi}(\mathbf{y})$** for the different models.
- To focus on average properties not depending on a specific data realisation, minimise the **expected Kullback-Leibler distance**

$$\mathbf{E}_{\mathbf{y}}[K(f_{\hat{\psi}(\mathbf{y})}, g)] = \mathbf{E}_{\mathbf{y}}[\mathbf{E}_{\mathbf{z}} [\log(g(\mathbf{z})) - \log(f_{\hat{\psi}(\mathbf{y})}(\mathbf{z}))]]]$$

- Since $g(\cdot)$ does not depend on the data, this is equivalent to minimising

$$-2 \mathbf{E}_{\mathbf{y}}[\mathbf{E}_{\mathbf{z}}[\log(f_{\hat{\psi}(\mathbf{y})}(\mathbf{z}))]] \quad (1)$$

(the expected **relative** Kullback-Leibler distance).

- The best available estimate for (1) is given by

$$-2 \log(f_{\hat{\psi}(\mathbf{y})}(\mathbf{y})).$$

- While (1) is a **predictive quantity** depending on both the data \mathbf{y} and an independent replication \mathbf{z} , the density and the parameter estimate are **evaluated for the same data**.

⇒ **Introduce a correction term.**

- Consider the **regularity conditions**
 - ψ is a k -dimensional parameter with parameter space $\Psi = \mathbb{R}^k$ (possibly achieved by a change of coordinates).
 - \mathbf{y} consists of independent and identically distributed replications y_1, \dots, y_n .
- In this case, an (asymptotically) unbiased estimate for (1) is given by

$$\text{AIC} = -2 \log(f_{\hat{\psi}(\mathbf{y})}(\mathbf{y})) + 2k.$$

Linear Mixed Models

- Mixed models form a very useful class of regression models with general form

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\mathbf{b} + \boldsymbol{\varepsilon}$$

where $\boldsymbol{\beta}$ are usual regression coefficients while \mathbf{b} are **random effects** with distributional assumption

$$\begin{bmatrix} \boldsymbol{\varepsilon} \\ \mathbf{b} \end{bmatrix} \sim \text{N} \left(\begin{bmatrix} \mathbf{0} \\ \mathbf{0} \end{bmatrix}, \begin{bmatrix} \sigma^2 \mathbf{I} & \mathbf{0} \\ \mathbf{0} & \mathbf{D} \end{bmatrix} \right).$$

- In the following, we will concentrate on mixed models with **only one variance component** where

$$\mathbf{b} \sim \text{N}(\mathbf{0}, \tau^2 \mathbf{I}) \quad \text{or} \quad \mathbf{b} \sim \text{N}(\mathbf{0}, \tau^2 \boldsymbol{\Sigma})$$

with $\boldsymbol{\Sigma}$ known.

- Special case I: Random intercept model for **longitudinal data**

$$y_{ij} = \mathbf{x}'_{ij}\boldsymbol{\beta} + b_i + \varepsilon_{ij}, \quad j = 1, \dots, J_i, \quad i = 1, \dots, I,$$

where i indexes individuals while j indexes **repeated observations** on the same individual.

- The random intercept b_i accounts for shifts in the individual level of response trajectories and therefore also for **intra-subject correlations**.

- Special case II: **Penalised spline smoothing** for nonparametric function estimation

$$y_i = m(x_i) + \varepsilon_i, \quad i = 1, \dots, n,$$

where $m(x)$ is a **smooth, unspecified function**.

- Approximating $m(x)$ in terms of a **spline basis of degree d** leads (for example) to the truncated power series representation

$$m(x) = \sum_{j=0}^d \beta_j x^j + \sum_{j=1}^K b_j (x - \kappa_j)_+^d$$

where $\kappa_1, \dots, \kappa_K$ denotes a sequence of knots.

- Assume random effects distribution $\mathbf{b} \sim \mathbf{N}(\mathbf{0}, \tau^2 \mathbf{I})$ for the basis coefficients of truncated polynomials to **enforce smoothness**.

- **Marginal perspective** on a mixed model:

$$\mathbf{y} \sim \text{N}(\mathbf{X}\boldsymbol{\beta}, \mathbf{V})$$

where

$$\mathbf{V} = \sigma^2 \mathbf{I} + \mathbf{ZDZ}'$$

- Interpretation: The random effects induce a **correlation structure** and therefore enable a proper statistical analysis of correlated data.
- **Conditional perspective** on a mixed model:

$$\mathbf{y}|\mathbf{b} \sim \text{N}(\mathbf{X}\boldsymbol{\beta} + \mathbf{Zb}, \sigma^2 \mathbf{I}).$$

- Interpretation: Random effects are **additional regression coefficients** (for example subject-specific effects in longitudinal data) that are estimated subject to a regularisation penalty.

- Interest in the following is on the selection of random effects: Compare

$$M_1 : \mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\mathbf{b} + \boldsymbol{\varepsilon}, \quad \mathbf{b} \sim \text{N}(\mathbf{0}, \tau^2 \boldsymbol{\Sigma})$$

and

$$M_2 : \mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}.$$

- Equivalent: Compare model with random effects ($\tau^2 > 0$) and without random effects ($\tau^2 = 0$).
- Random Intercept: $\tau^2 > 0$ versus $\tau^2 = 0$ corresponds to the **inclusion and exclusion of the random intercept** and therefore to the presence or absence of intra-individual correlations.
- Penalised splines: $\tau^2 > 0$ versus $\tau^2 = 0$ differentiates between a spline model and a simple polynomial model. In particular, we can compare **linear versus nonlinear models**.

Akaike Information Criteria in Linear Mixed Models

- In linear mixed models, **two variants of AIC** are conceivable based on either the marginal or the conditional distribution.
- The **marginal AIC relies** on the marginal model

$$\mathbf{y} \sim \mathbf{N}(\mathbf{X}\boldsymbol{\beta}, \mathbf{V})$$

and is defined as

$$\text{mAIC} = -2l(\mathbf{y}|\hat{\boldsymbol{\beta}}, \hat{\tau}^2, \hat{\sigma}^2) + 2(p + 2),$$

where the **marginal likelihood** is given by

$$l(\mathbf{y}|\hat{\boldsymbol{\beta}}, \hat{\tau}^2, \hat{\sigma}^2) = -\frac{1}{2} \log(|\hat{\mathbf{V}}|) - \frac{1}{2}(\mathbf{y} - \mathbf{X}\hat{\boldsymbol{\beta}})' \hat{\mathbf{V}}^{-1} (\mathbf{y} - \mathbf{X}\hat{\boldsymbol{\beta}})$$

and $p = \dim(\boldsymbol{\beta})$.

- The **conditional AIC** relies on the conditional model

$$\mathbf{y}|\mathbf{b} \sim \text{N}(\mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\mathbf{b}, \sigma^2\mathbf{I})$$

and is defined as

$$\text{cAIC} = -2l(\mathbf{y}|\hat{\boldsymbol{\beta}}, \hat{\mathbf{b}}, \hat{\tau}^2, \sigma^2) + 2(\rho + 1),$$

where

$$l(\mathbf{y}|\hat{\boldsymbol{\beta}}, \hat{\mathbf{b}}, \hat{\tau}^2, \sigma^2) = -\frac{n}{2} \log(\hat{\sigma}^2) - \frac{1}{2\hat{\sigma}^2} (\mathbf{y} - \mathbf{X}\hat{\boldsymbol{\beta}} - \mathbf{Z}\hat{\mathbf{b}})' (\mathbf{y} - \mathbf{X}\hat{\boldsymbol{\beta}} - \mathbf{Z}\hat{\mathbf{b}})$$

is the **conditional likelihood** and

$$\rho = \text{tr} \left(\left(\begin{pmatrix} \mathbf{X}'\mathbf{X} & \mathbf{X}'\mathbf{Z} \\ \mathbf{Z}'\mathbf{X} & \mathbf{Z}'\mathbf{Z} + \sigma^2/\tau^2\boldsymbol{\Sigma} \end{pmatrix}^{-1} \begin{pmatrix} \mathbf{X}'\mathbf{X} & \mathbf{X}'\mathbf{Z} \\ \mathbf{Z}'\mathbf{X} & \mathbf{Z}'\mathbf{Z} \end{pmatrix} \right) \right)$$

are the **effective degrees of freedom** (trace of the hat matrix).

Marginal AIC

- Model M_1 ($\tau^2 > 0$) is preferred over M_2 ($\tau^2 = 0$) when

$$\begin{aligned} \text{mAIC}_1 < \text{mAIC}_2 &\Leftrightarrow -2l(\mathbf{y}|\hat{\boldsymbol{\beta}}_1, \hat{\tau}^2, \hat{\sigma}_1^2) + 2(p+2) < -2l(\mathbf{y}|\hat{\boldsymbol{\beta}}_2, \mathbf{0}, \hat{\sigma}_2^2) + 2(p+1) \\ &\Leftrightarrow 2l(\mathbf{y}|\hat{\boldsymbol{\beta}}_1, \hat{\tau}^2, \hat{\sigma}_1^2) - 2l(\mathbf{y}|\hat{\boldsymbol{\beta}}_2, \mathbf{0}, \hat{\sigma}_2^2) > 2. \end{aligned}$$

- The left hand side is simply the test statistic for a **likelihood ratio test on $\tau^2 = 0$ versus $\tau^2 > 0$** .
- Under standard asymptotics, we would have

$$2l(\mathbf{y}|\hat{\boldsymbol{\beta}}_1, \hat{\tau}^2, \hat{\sigma}_1^2) - 2l(\mathbf{y}|\hat{\boldsymbol{\beta}}_2, \mathbf{0}, \hat{\sigma}_2^2) \stackrel{a, H_0}{\sim} \chi_1^2$$

and the marginal AIC would have a type 1 error of

$$P(\chi_1^2 > 2) \approx 0.1572992$$

- Common interpretation: AIC selects **rather too many than too few effects**.

- In contrast to the regularity conditions for likelihood ratio tests, τ^2 is on the **boundary of the parameter space** for model M_2 .
- The classical assumptions underlying the derivation of AIC are also not fulfilled.
- Consequences:
 - The marginal AIC is positively biased for twice the expected relative Kullback-Leibler-Distance.
 - The bias is dependent on the true unknown parameters in the random effects covariance matrix and this dependence does not vanish asymptotically.
 - Compared to an unbiased criterion, the marginal AIC **favors smaller models excluding random effects**.
- This contradicts the usual intuition that the AIC picks rather too many than too few effects.

Conditional AIC

- Vaida & Blanchard (2005) have shown that the conditional AIC from above is asymptotically unbiased for the expected relative Kullback Leibler distance for **given random effects covariance matrix**.
- Intuition: Result should carry over when using a **consistent estimate**.
- Surprisingly, this is not the case: The complex model including the random effect is chosen **whenever $\hat{\tau}^2 > 0$** :

$$\hat{\tau}^2 > 0 \quad \Leftrightarrow \quad \text{cAIC}(\hat{\tau}^2) < \text{cAIC}(0)$$

$$\hat{\tau}^2 = 0 \quad \Leftrightarrow \quad \text{cAIC}(\hat{\tau}^2) = \text{cAIC}(0).$$

- Principal difficulty: The degrees of freedom in the cAIC are **estimated from the same data as the model parameters**.

- Liang et al. (2008) propose a **corrected conditional AIC**, where the degrees of freedom ρ are replaced by the estimate

$$\hat{\rho} = \sum_{i=1}^n \frac{\partial \hat{y}_i}{\partial y_i} = \text{tr} \left(\frac{\partial \hat{\mathbf{y}}}{\mathbf{y}} \right).$$

- The resulting corrected conditional AIC shows **satisfactory theoretical properties**.
- However, it is **computationally cumbersome**:
 - Liang et al. suggested to approximate the derivatives numerically (by adding small perturbations to the data).
 - Numerical approximations require n and $2n$ model fits. In an application with 1,600 Observations and 64 candidate models, computing the corrected conditional AICs would take about 110 days.
- We have developed a **closed form representation of $\hat{\rho}$** that is available almost instantaneously.

Summary

- The marginal AIC suffers from the same theoretical difficulties as likelihood ratio tests on the boundary of the parameter space.
- The marginal AIC is biased towards simpler models excluding random effects.
- The conventional conditional AIC tends to select too many variables.
- Whenever a random effects variance is estimated to be positive, the corresponding effect will be included.
- The corrected conditional AIC rectifies this difficulty and is now available in closed form.

- References:
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